Algorithm Efficiency and Sorting

Measuring the Efficiency of Algorithms

Analysis of algorithms

- Provides tools for contrasting the efficiency of different methods of solution
- A comparison of algorithms
 - Should focus of significant differences in efficiency
 - Should not consider reductions in computing costs due to clever coding tricks

Measuring the Efficiency of Algorithms

- Three difficulties with comparing programs instead of algorithms
 - How are the algorithms coded?
 - What computer should you use?
 - What data should the programs use?
- Algorithm analysis should be independent of
 - Specific implementations
 - Computers
 - Data

The Execution Time of Algorithms

- Counting an algorithm's operations is a way to access its efficiency
 - An algorithm's execution time is related to the number of operations it requires
 - Examples
 - Traversal of a linked list
 - The Towers of Hanoi
 - Nested Loops

Algorithm Growth Rates

- An algorithm's time requirements can be measured as a function of the problem size
- An algorithm's growth rate
 - Enables the comparison of one algorithm with another
 - Examples

Algorithm A requires time proportional to n² Algorithm B requires time proportional to n

Algorithm efficiency is typically a concern for large problems only

Algorithm Growth Rates

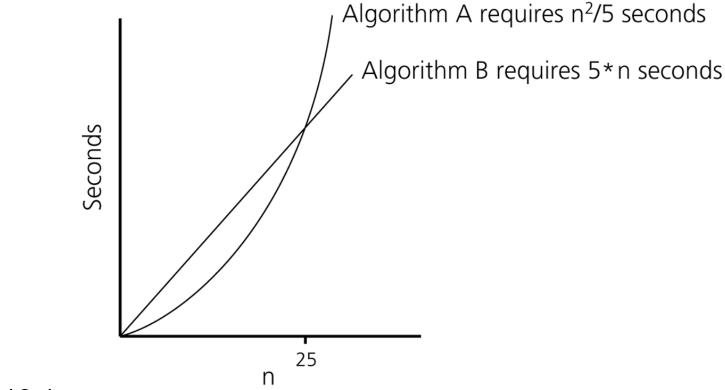


Figure 10-1

Time requirements as a function of the problem size *n*

Definition of the order of an algorithm

Algorithm A is order f(n) – denoted O(f(n)) – if constants k and n_0 exist such that A requires no more than k * f(n) time units to solve a problem of size $n \ge n_0$

Growth-rate function

A mathematical function used to specify an algorithm's order in terms of the size of the problem

Big O notation

- A notation that uses the capital letter O to specify an algorithm's order
- Example: O(f(n))

	n						
Function	10	100	1,000	10,000	100,000	1,000,000	
1	1	1	1	1	1	1	
log ₂ n	3	6	9	13	16	19	
n	10	10 ²	10 ³	104	10 ⁵	10 ⁶	
n ∗log₂n	30	664	9,965	10 ⁵	106	107	
n ²	10 ²	104	10 ⁶	10 ⁸	10 ¹⁰	10 ¹²	
n ³	10 ³	10 ⁶	10 ⁹	10 ¹²	10 ¹⁵	10 ¹⁸	
2 ⁿ	10 ³	10 ³⁰	10 ³⁰	¹ 10 ^{3,01}	¹⁰ 10 ^{30,}	¹⁰³ 10 ^{301,030}	

Figure 10-3a

(a)

A comparison of growth-rate functions: a) in tabular form

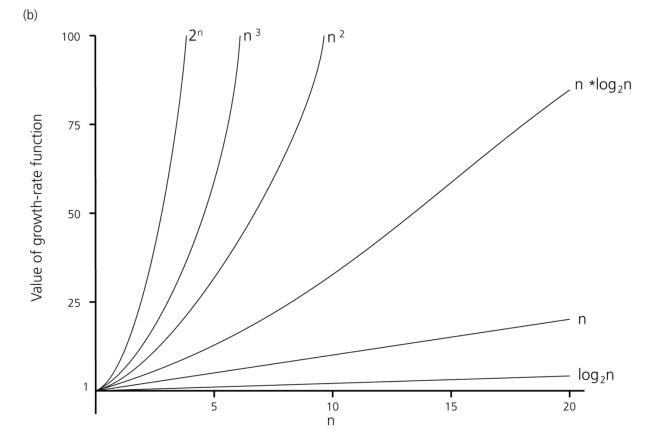


Figure 10-3b

A comparison of growth-rate functions: b) in graphical form

- Order of growth of some common functions $O(1) < O(\log_2 n) < O(n) < O(n * \log_2 n) < O(n^2) < O(n^3) < O(2^n)$
- Properties of growth-rate functions
 - You can ignore low-order terms
 - You can ignore a multiplicative constant in the high-order term
 - O(f(n)) + O(g(n)) = O(f(n) + g(n))

- Worst-case and average-case analyses
 - An algorithm can require different times to solve different problems of the same size
 - Worst-case analysis
 - A determination of the maximum amount of time that an algorithm requires to solve problems of size n
 - Average-case analysis
 - A determination of the average amount of time that an algorithm requires to solve problems of size n

Keeping Your Perspective

- Throughout the course of an analysis, keep in mind that you are interested only in significant differences in efficiency
- When choosing an ADT's implementation, consider how frequently particular ADT operations occur in a given application
 - Some seldom-used but critical operations must be efficient

Keeping Your Perspective

- If the problem size is always small, you can probably ignore an algorithm's efficiency
 - Weigh the trade-offs between an algorithm's time requirements and its memory requirements
- Compare algorithms for both style and efficiency
- Order-of-magnitude analysis focuses on large problems

The Efficiency of Searching Algorithms

Sequential search

- Strategy
 - Look at each item in the data collection in turn, beginning with the first one
 - Stop when
 - You find the desired item
 - You reach the end of the data collection

The Efficiency of Searching Algorithms

Sequential search

- Efficiency
 - Worst case: O(n)
 - Average case: O(n)
 - Best case: O(1)

The Efficiency of Searching Algorithms

Binary search

- Strategy
 - To search a sorted array for a particular item
 - Repeatedly divide the array in half
 - Determine which half the item must be in, if it is indeed present, and discard the other half
- Efficiency
 - Worst case: O(log₂n)
- For large arrays, the binary search has an enormous advantage over a sequential search

Sorting Algorithms and Their Efficiency

- Sorting
 - A process that organizes a collection of data into either ascending or descending order
 - Categories of sorting algorithms
 - An internal sort
 - Requires that the collection of data fit entirely in the computer's main memory
 - An external sort
 - The collection of data will not fit in the computer's main memory all at once but must reside in secondary storage

Sorting Algorithms and Their Efficiency

- Data items to be sorted can be
 - Integers
 - Character strings
 - Objects
- Sort key
 - The part of a record that determines the sorted order of the entire record within a collection of records

Selection Sort

- Selection sort
 - Strategy
 - Select the largest item and put it in its correct place
 - Select the next largest item and put it in its correct place, etc.

Shaded elements are selected; boldface elements are in order.

Figure 10-4

A selection sort of an array of

five integers

Initial array:2After 1st swap:2After 2nd swap:1After 3rd swap:1After 4th swap:1

29	10	14	37	13
29	10	14	13	37
13	10	14	29	37
13	10	14	29	37
10	13	14	29	37

Selection Sort

- Analysis
 - Selection sort is O(n²)
- Advantage of selection sort
 - It does not depend on the initial arrangement of the data
- Disadvantage of selection sort
 - It is only appropriate for small n

Selection Code

// This code will compile with warnings about unchecked exceptions

```
public class SortsClass {
```

```
public static void selectionSort(Comparable[] theArray,
int n) {
```

// -----

// Sorts the items in an array into ascending order.

// Precondition: theArray is an array of n items.

// Postcondition: theArray is sorted into

// ascending order.

// Calls: indexOfLargest.

// -----

// last = index of the last item in the subarray of

// items yet to be sorted

// largest = index of the largest item found

Selection Code

```
for (int last = n-1; last >= 1; last--) {
```

// Invariant: theArray[last+1..n-1] is sorted

// and > theArray[0..last]

// select largest item in theArray[0..last]

int largest = indexOfLargest(theArray, last+1);

// swap largest item theArray[largest] with

// theArray[last]

```
Comparable temp = theArray[largest];
```

```
theArray[largest] = theArray[last];
```

```
theArray[last] = temp;
```

```
} // end for
```

```
} // end selectionSort
```

Selection Code

private static int indexOfLargest(Comparable[] theArray,

int size) {

// -----

```
// Finds the largest item in an array.
```

// Precondition: theArray is an array of size items;

// size >= 1.

// Postcondition: Returns the index of the largest

// item in the array.

// -----

int indexSoFar = 0; // index of largest item found so far // Invariant: theArray[indexSoFar]>=theArray[0..currIndex-1] for (int currIndex = 1; currIndex < size; ++currIndex) { if (theArray[currIndex].compareTo(theArray[indexSoFar])>0) { indexSoFar = currIndex; } // end if } // end for return indexSoFar; // index of largest item

}// end indexOfLargest

Performance Analysis

Bubble Sort

- Bubble sort
 - Strategy
 - Compare adjacent elements and exchange them if they are out of order
 - Comparing the first two elements, the second and third elements, and so on, will move the largest (or smallest) elements to the end of the array
 - Repeating this process will eventually sort the array into ascending (or descending) order

Bubble Sort

(a) Pass 1

(b) Pass 2

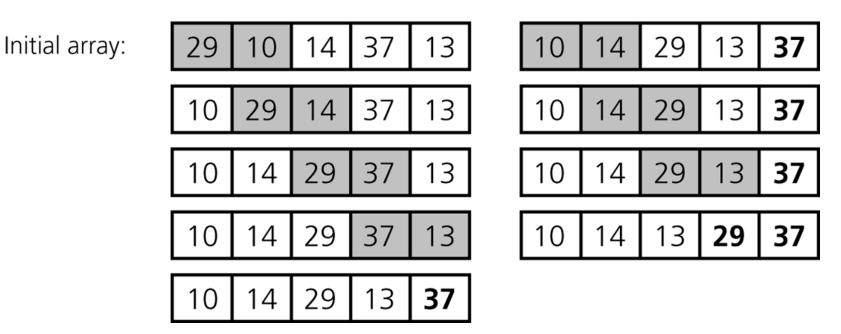


Figure 10-5

The first two passes of a bubble sort of an array of five integers: a) pass 1; b) pass 2

Bubble Sort Code

public static void bubbleSort(Comparable[] theArray, int n) {

// -----

```
// Sorts the items in an array into ascending order.
// Precondition: theArray is an array of n items.
// Postcondition: theArray is sorted into ascending
// order.
// -----
 boolean sorted = false; // false when swaps occur
 for (int pass = 1; (pass < n) && !sorted; ++pass) {
 // Invariant: theArray[n+1-pass..n-1] is sorted
 // and > theArray[0..n-pass]
   sorted = true; // assume sorted
   for (int index = 0; index < n-pass; ++index) {</pre>
   // Invariant: theArray[0..index-1] <= theArray[index]</pre>
    int nextIndex = index + 1;
    if (theArray[index].compareTo(theArray[nextIndex]) > 0) {
    // exchange items
      Comparable temp = theArray[index];
      theArray[index] = theArray[nextIndex];
      theArray[nextIndex] = temp;
      sorted = false; // signal exchange
    }// end if
   }// end for
 // Assertion: theArray[0..n-pass-1] < theArray[n-pass]</pre>
 }// end for
}// end bubbleSort
```

Bubble Sort Analysis

- Analysis
 - Worst case: O(n²)
 - Best case: O(n)

Insertion Sort

- Insertion sort
 - Strategy
 - Partition the array into two regions: sorted and unsorted
 - Take each item from the unsorted region and insert it into its correct order in the sorted region

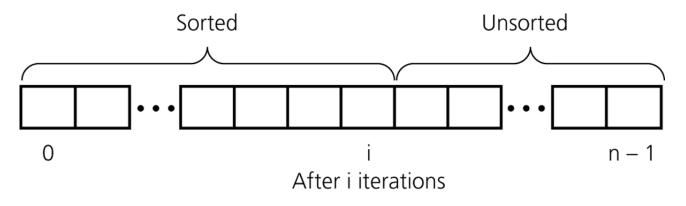
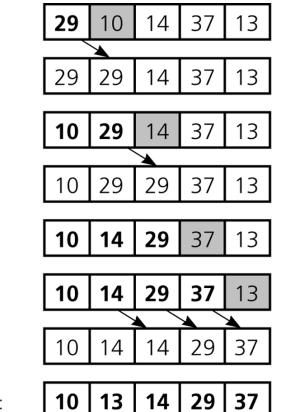


Figure 10-6

An insertion sort partitions the array into two regions

Insertion Sort

Initial array:



Sorted array:

Figure 10-7

An insertion sort of an array of five integers.

Copy 10

Shift 29

Insert 10; copy 14

Shift 29

Insert 14; copy 37, insert 37 on top of itself

Copy 13

Shift 37, 29, 14

Insert 13

Insertion Sort Code

public static void insertionSort(Comparable[] theArray,

int n) {

// -----

// Sorts the items in an array into ascending order.

// Precondition: theArray is an array of n items.

// Postcondition: theArray is sorted into ascending
// order

// order.

// -----

// unsorted = first index of the unsorted region,

// loc = index of insertion in the sorted region,

// nextItem = next item in the unsorted region

// initially, sorted region is theArray[0],

// unsorted region is theArray[1..n-1];

for (int unsorted = 1; unsorted < n; ++unsorted) {</pre>

// Invariant: theArray[0..unsorted-1] is sorted

// find the right position (loc) in

// theArray[0..unsorted] for theArray[unsorted],

// which is the first item in the unsorted

// region; shift, if necessary, to make room

Insertion Sort Code

Comparable nextItem = theArray[unsorted];

```
int loc = unsorted;
while ((loc > 0) &&
  (theArray[loc-1].compareTo(nextItem) > 0)) {
    // shift theArray[loc-1] to the right
        theArray[loc] = theArray[loc-1];
        loc--;
     } // end while
     // insert nextItem into sorted region
        theArray[loc] = nextItem;
     } // end for
} // end insertionSort
```

Insertion Sort

- Analysis
 - Worst case: O(n²)
 - For small arrays
 - Insertion sort is appropriate due to its simplicity
 - For large arrays
 - Insertion sort is prohibitively inefficient

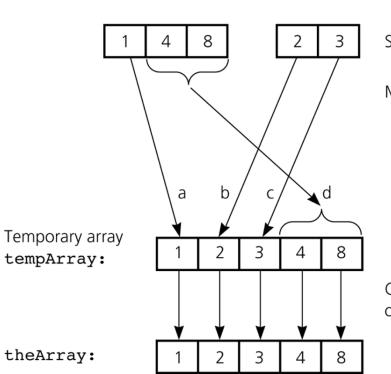
Mergesort

- Important divide-and-conquer sorting algorithms
 - Mergesort
 - Quicksort
- Mergesort
 - A recursive sorting algorithm
 - Gives the same performance, regardless of the initial order of the array items
 - Strategy
 - Divide an array into halves
 - Sort each half
 - Merge the sorted halves into one sorted array

Mergesort

theArray:

8



3

4

2

Divide the array in half

Sort the halves

Merge the halves:

- a. 1 < 2, so move 1 from left half to tempArray
- b. 4 > 2, so move 2 from right half to tempArray
- c. 4 > 3, so move 3 from right half to tempArray
- d. Right half is finished, so move rest of left half to tempArray

Copy temporary array back into original array

Figure 10-8

A mergesort with an auxiliary temporary array

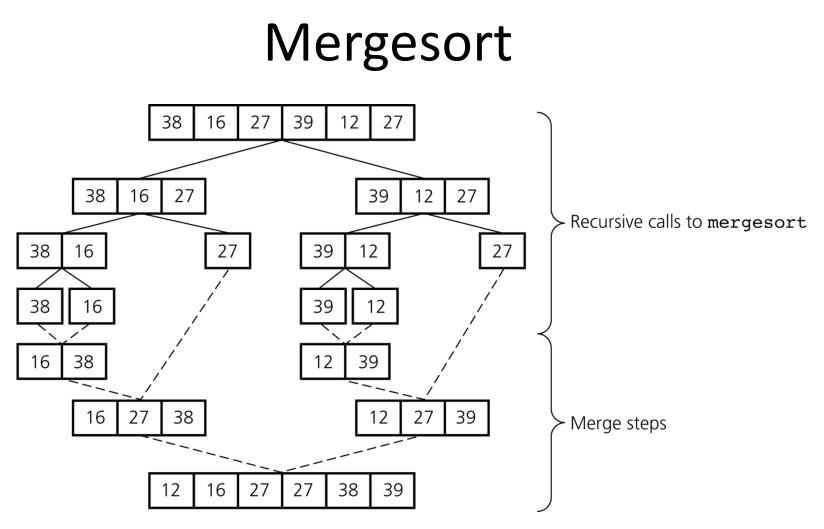


Figure 10-9

A mergesort of an array of six integers

Mergesort

- Analysis
 - Worst case: $O(n * \log_2 n)$
 - Average case: $O(n * \log_2 n)$
 - Advantage
 - It is an extremely efficient algorithm with respect to time
 - Drawback
 - It requires a second array as large as the original array

Mergesort

Click <u>here</u> to open the mergesort program

- Quicksort
 - A divide-and-conquer algorithm
 - Strategy
 - Partition an array into items that are less than the pivot and those that are greater than or equal to the pivot
 - Sort the left section
 - Sort the right section

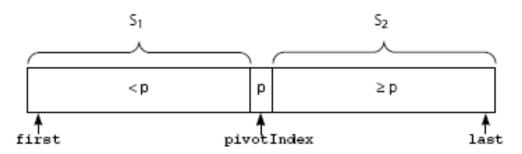


Figure 10-12

A partition about a pivot

- Using an invariant to develop a partition algorithm
 - Invariant for the partition algorithm

The items in region S_1 are all less than the pivot, and those in S_2 are all greater than or equal to the pivot

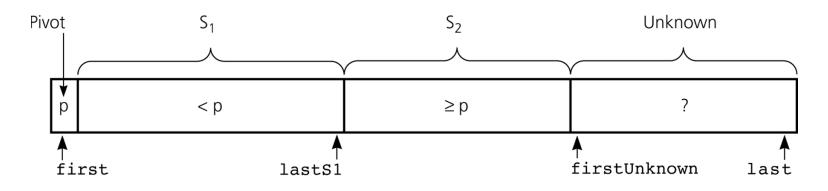
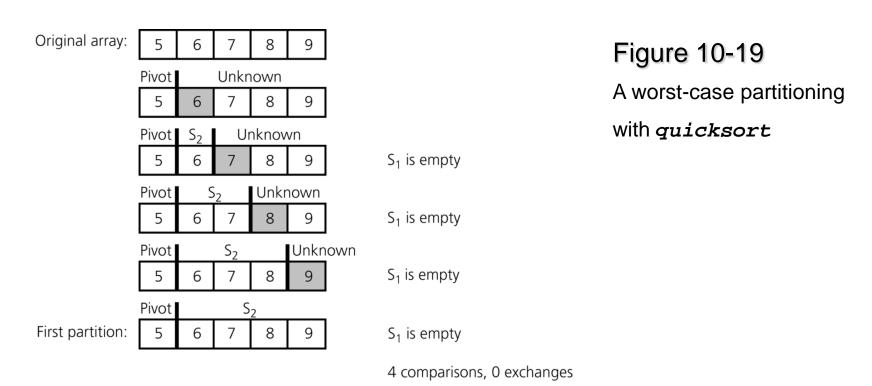


Figure 10-14

Invariant for the partition algorithm

- Analysis
 - Worst case
 - quicksort is O(n²) when the array is already sorted and the smallest item is chosen as the pivot



• Analysis

- Average case
 - quicksort is O(n * log₂n) when S₁ and S₂ contain the same or nearly the same – number of items arranged at random

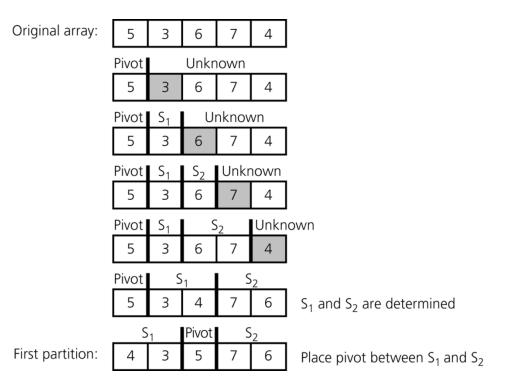


Figure 10-20

A average-case partitioning with

quicksort

- Analysis
 - quicksort is usually extremely fast in practice
 - Even if the worst case occurs, quicksort's performance is acceptable for moderately large arrays
 - Click <u>here</u> to open the quicksort program

Radix Sort

- Radix sort
 - Treats each data element as a character string
 - Strategy
 - Repeatedly organize the data into groups according to the ith character in each element
- Analysis
 - Radix sort is O(n)

Radix Sort

0123, 2154, 0222, 0004, 0283, 1560, 1061, 2150 (1560, 2150) (1061) (0222) (0123, 0283) (2154, 0004) 1560, 2150, 1061, 0222, 0123, 0283, 2154, 0004 (0004) (0222, 0123) (2150, 2154) (1560, 1061) (0283) 0004, 0222, 0123, 2150, 2154, 1560, 1061, 0283 (0004, 1061) (0123, 2150, 2154) (0222, 0283) (1560) 0004, 1061, 0123, 2150, 2154, 0222, 0283, 1560 (0004, 0123, 0222, 0283) (1061, 1560) (2150, 2154) 0004, 0123, 0222, 0283, 1061, 1560, 2150, 2154

Figure 10-21

A radix sort of eight integers

Original integers Grouped by fourth digit Combined Grouped by third digit Combined Grouped by second digit Combined Grouped by first digit

A Comparison of Sorting Algorithms

	Worst case	Average case
Selection sort Bubble sort Insertion sort	n ² n ² n ²	n ² n ² n ²
Mergesort	n * log n	n * log n
Quicksort	n ²	n * log n
Radix sort	n	n
Treesort	n ²	n * log n
Heapsort	n * log n	n * log n

Figure 10-22

Approximate growth rates of time required for eight sorting algorithms

Summary

- Order-of-magnitude analysis and Big O notation measure an algorithm's time requirement as a function of the problem size by using a growth-rate function
- To compare the inherit efficiency of algorithms
 - Examine their growth-rate functions when the problems are large
 - Consider only significant differences in growth-rate functions

Summary

- Worst-case and average-case analyses
 - Worst-case analysis considers the maximum amount of work an algorithm requires on a problem of a given size
 - Average-case analysis considers the expected amount of work an algorithm requires on a problem of a given size
- Order-of-magnitude analysis can be used to choose an implementation for an abstract data type
- Selection sort, bubble sort, and insertion sort are all O(n²) algorithms
- Quicksort and mergesort are two very efficient sorting algorithms

Acknowledgement

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